



# WP1: A<sup>3</sup> Concept of Operations

---

## Overview

Petr Cášek

iFly Mid Term Review, September 29, 2009



**Honeywell**

# WP1: A<sup>3</sup> Concept of Operations

Honeywell

## WP1 Goal:

Develop highly **automated ATM design for en-route traffic** based on **autonomous aircraft concept (ASAS Self Separation)**.

## WP1 Structure:

- ✓ WP1.1: A<sup>3</sup> High-level ConOps
- ✓ WP1.2: A<sup>3</sup> Airline Strategy Concept
- ✓ WP1.3: A<sup>3</sup> ConOps

## Main Elements:

- **Concept Enablers:**
  - Communications
  - Information sharing
- **Autonomous Flight Rules**
  - Mid Term CR based on Priority Rules
  - Short Term CR based on Implicit Coordination
- **Priority Rules guidelines**
- **A possible high-level airborne system design**
- **Human factors aspects**

# A3 ConOps Team

Honeywell

## iFly WP1 Authors:

- Frank Bussink (NLR)
- Ignacio Echegoyen (former Isdefe)
- Petr Cásek (Honeywell)
- Gustavo Cuevas (Isdefe)
- Aavo Luuk (University of Tartu)
- Claudia Keinrath (Honeywell)
- Rosa Weber (Honeywell)
- José García García (Isdefe)



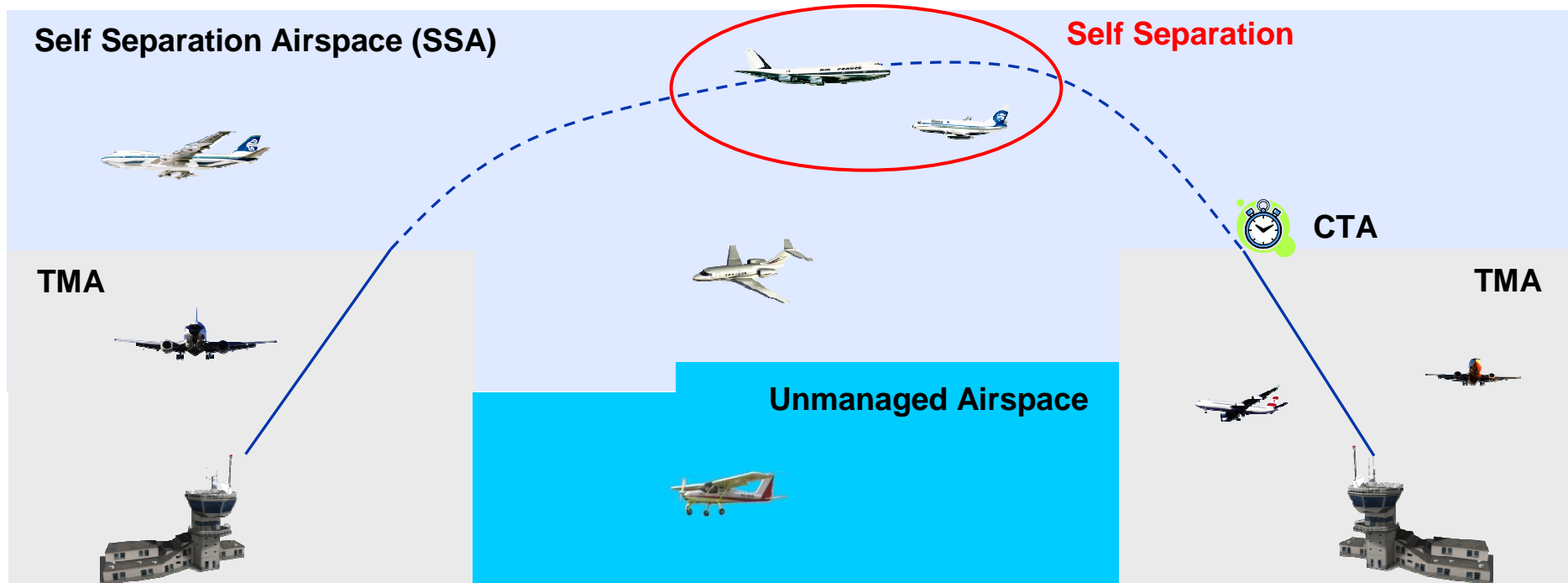
## iFly Partners and Reviewers contributing with their feedback

## iFly A3 ConOps has also benefitted from NASA's pro-bono involvement:

- NASA's advanced airborne self separation ConOps and research
- Active iFly participation by NASA Langley ATM Research Team
  - David Wing, Maria Consiglio
  - Frank Bussink, previously at LaRc on loan from NLR

# Scope of Self Separation in iFly

Honeywell



## iFly's Scope:

- ✓ En-route phase of the flight
- ✓ All aircraft are equipped to self separate
- ✓ No ATC involvement
- ✓ Ground information sharing support (SWIM) available

# Autonomous Aircraft Concept Traits

Honeywell

## Requirement



Airborne Separation Management

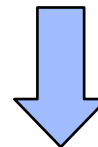
## Opportunity



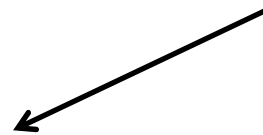
Onboard Trajectory Management

## Key Enabler

Situation Awareness (Information availability)



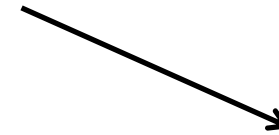
Information Sharing Process



Reliable



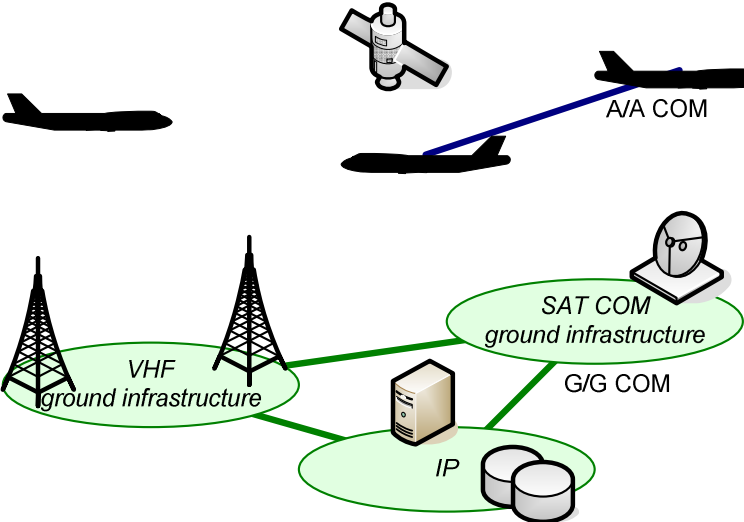
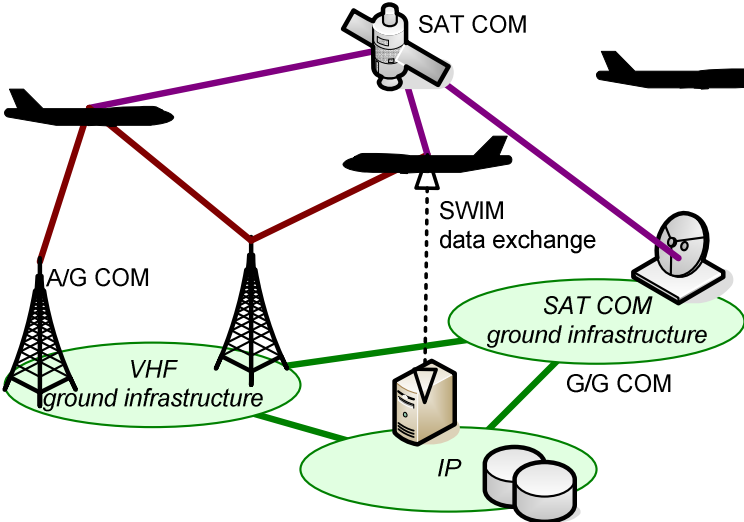
Continuous



Effective

# Data Link Communications (Traffic Data)

Reception of data broadcasted by other aircraft



Querying ground infrastructure (e.g., SWIM)  
Direct querying another aircraft

# Information Sharing Support

## Information Sharing Process

**Level 1: Air–Air Broadcast, State only**

**Level 2: Air–Air Broadcast, State + Intent**

**Level 3: Air–Air Broadcast + SWIM support, State + Intent**

## SM Limitations

- Air–Air data link range
- CD further limited by accuracy of state-based TP
- No information back up

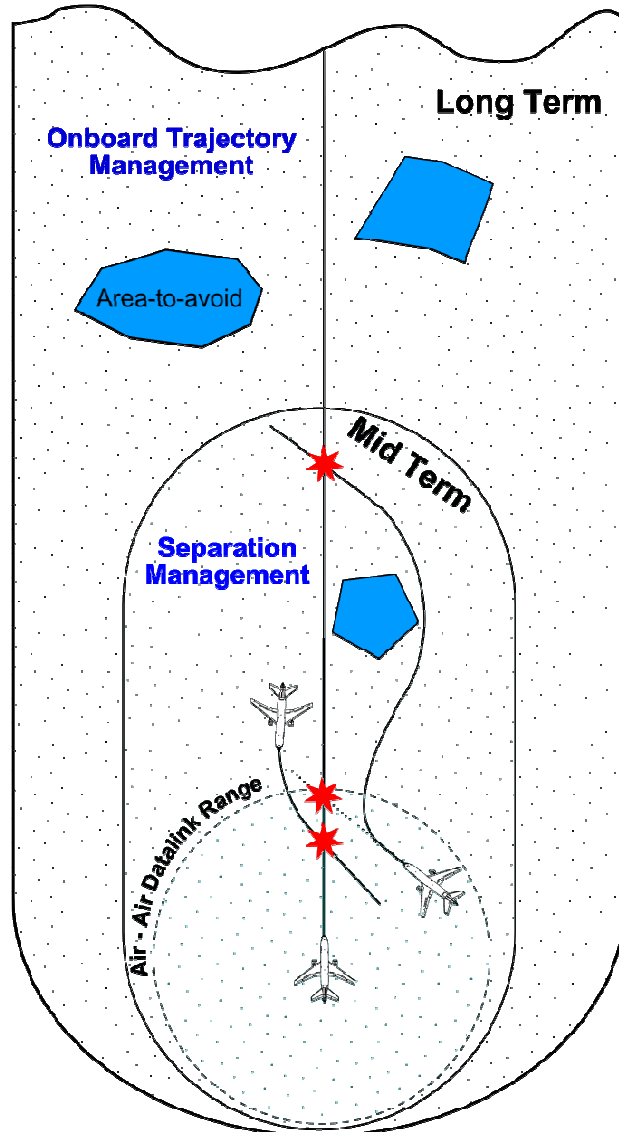
- Air–Air data link range
- No information back up

- Range defined by the area of interest (in principle)
- CD limited by the range of available intent information
- Information back up (point-to-point communication, SWIM)

**iFly considers Level 3, but performance and safety assessment may be performed for multiple levels.**

# Information Sharing – Situation Awareness

Honeywell

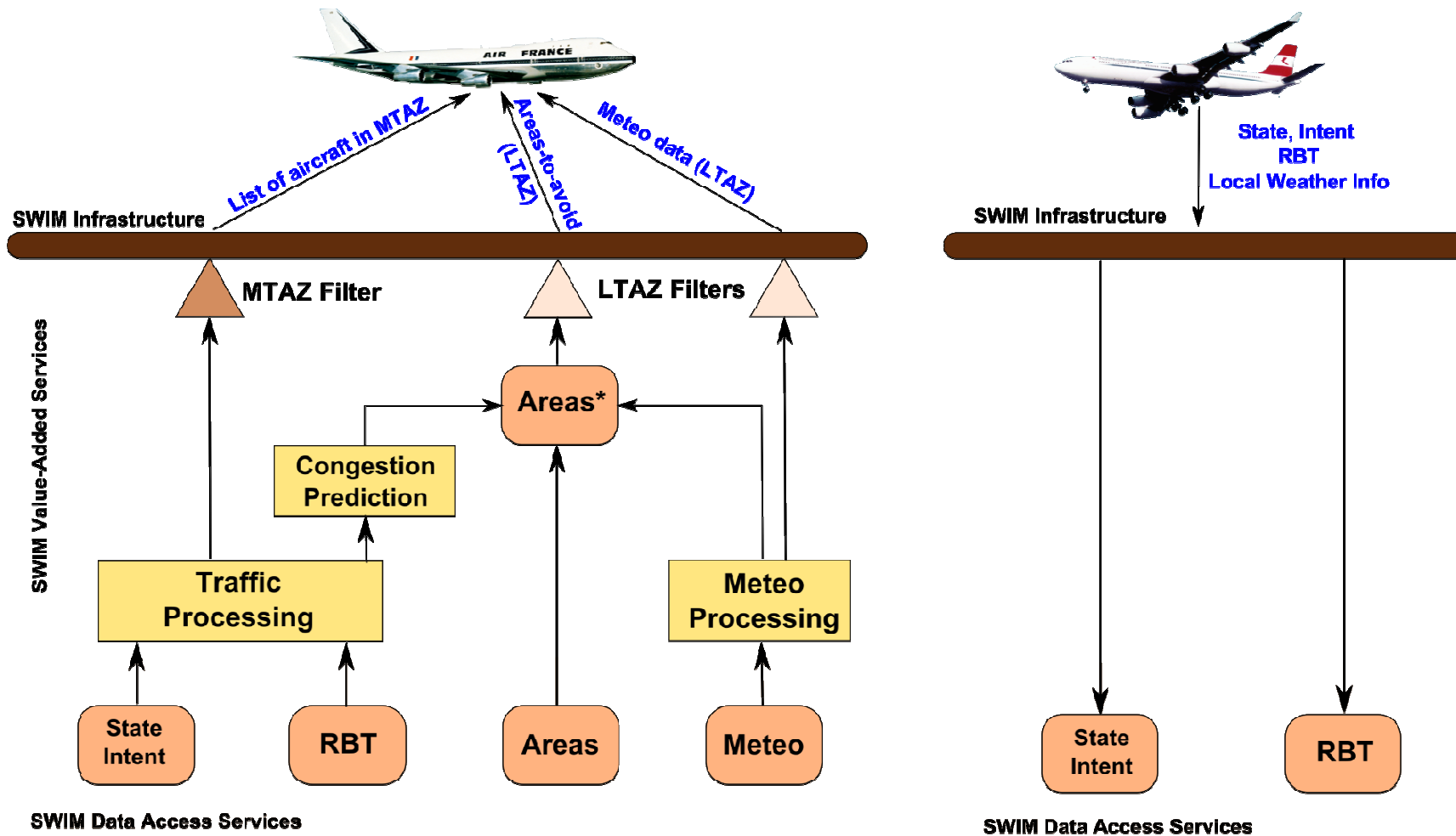


## Areas of interest:

- **Long Term Awareness Zone(LTAZ)**
  - relevant for Trajectory Management (optimization)
- **Mid Term Awareness Zone(MTAZ)**
  - used for Separation Management
- **Air-Air Data link Range**
  - additional state-based Conflict Detection



# SWIM and Envisioned Functionality



# Possible A<sup>3</sup> Airborne System Architecture



## Information Management

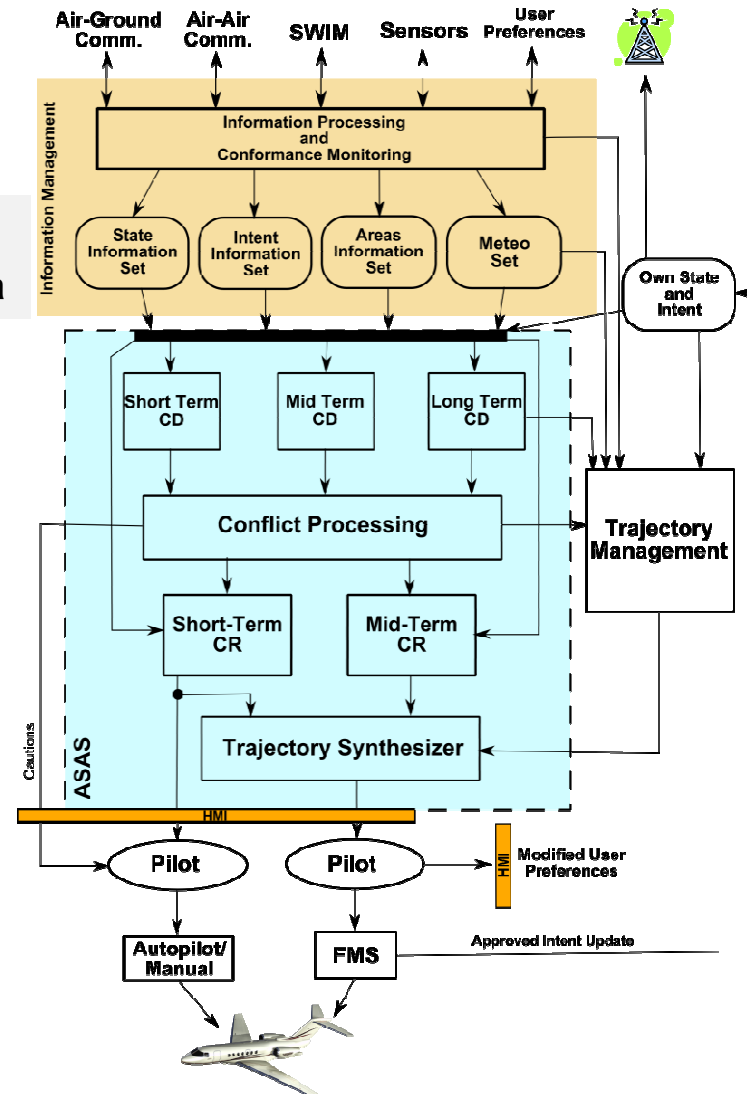
- Shields communications details
- Collect and process required data

## Separation & Trajectory Management

- Situation Assessment
- Resolution Advisories

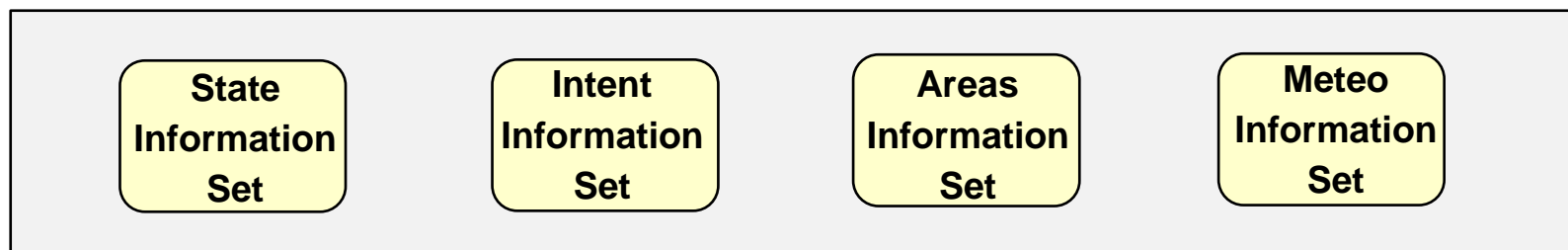
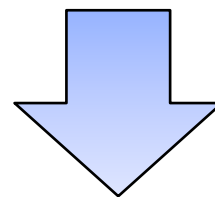
## Human Machine Interface

- Situation Awareness
- Flight changes advisories



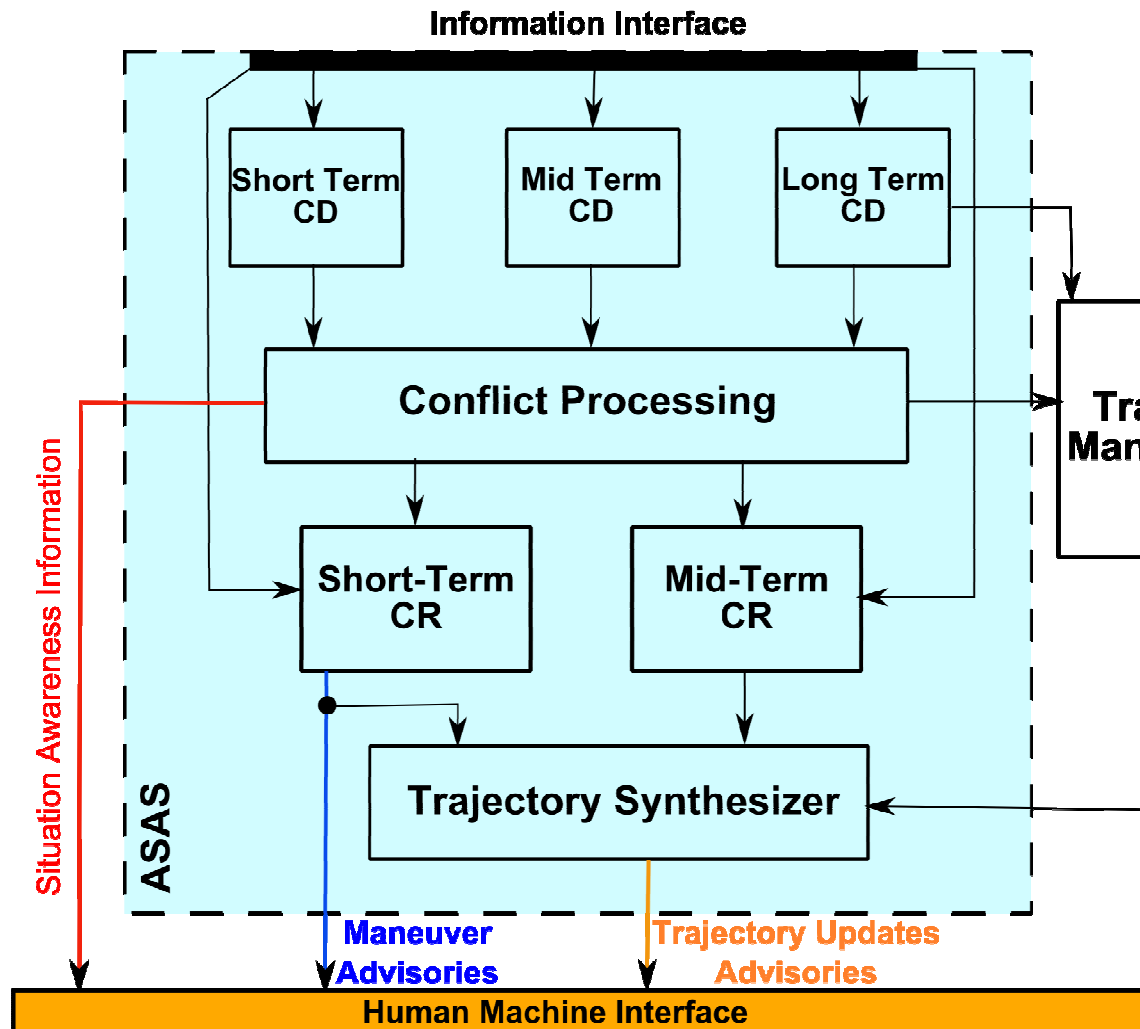
# Onboard Information Management

- ✓ Process all incoming broadcasted data
- ✓ Process the list of MTAZ traffic
- ✓ Query aircraft or SWIM for missing information
- ✓ Process areas-to-avoid, uploaded meteo data and data from sensors (weather radar, EGPWS)
- ✓ Monitor the conformance of aircraft to the intent
- ✓ Data fusion to determine the most probable trajectories of aircraft



# CD&R And Trajectory Management

Honeywell



## Mid Term Conflict:

1. Predicted LoS
2. Potential CR risk (complex situation)
  - Complexity, or
  - Maneuvering flexibility

## Short Term Conflict:

- State-based predicted LoS

## Long Term Conflict:

- Predicted LoS with Areas-to-avoid

# HMI Airborne System Requirements

- Provide aircrew with automation and decision support tools to ensure planned trajectory is clear of traffic, weather and restricted airspace
  - Integrated ownship and surveillance (ADS-B/C) data visualization
  - Real-time traffic, flow management and airspace hazard data;
  - Complementary (visual/aural) conflict alerting and multiple resolution maneuvering options

**BUT...**

## Critical to the aircrew

- HMI must be designed to allow for a quick and easy data input/understanding, which is tailored to users needs
- Appropriate level of automation
- Appropriate level of information
  - Situation awareness needs of ATM & aircrew



# A<sup>3</sup> ConOps – Dissemination

---

Honeywell

## **Presentations of A<sup>3</sup> Concept of Operations:**

- ✓ ***iFly: ASAS Self Separation – Airborne Perspective;***  
Presentation at ASAS-TN Workshop in Rome 2008, (Petr Casek and Rosa Weber).
- ✓ ***Airborne System for Self Separation in Trajectory-Base Airspace;*** paper + presentation at 7<sup>th</sup> Eurocontrol Innovative ATM Research Workshop, EEC Bretigny 2008 (Petr Casek and Claudia Keinrath).

# Thank You!



## Any Questions...



**Honeywell**